

PAPER • OPEN ACCESS

## Integrable hierarchies of Heisenberg ferromagnet equation

To cite this article: G. Nugmanova and A. Azimkhanova 2016 *J. Phys.: Conf. Ser.* **738** 012132

View the [article online](#) for updates and enhancements.

You may also like

- [Another look through Heisenberg's microscope](#)  
Stephen Boughn and Marcel Reginatto
- [The  \$q\$ -Hermite Polynomial and the Representations of Heisenberg and Quantum Heisenberg Algebra](#)  
Xi-Wen Guan, Dian-Min Tong and Huan-Qiang Zhou
- [Renormalization of Dirac Delta Potentials Through Minimal Extension of Heisenberg Algebra](#)  
Fatih Erman



The Electrochemical Society  
Advancing solid state & electrochemical science & technology

243rd ECS Meeting with SOFC-XVIII

Boston, MA • May 28 – June 2, 2023

**Abstract Submission Extended  
Deadline: December 16**

[Learn more and submit!](#)

# Integrable hierarchies of Heisenberg ferromagnet equation

**G. Nugmanova, A. Azimkhanova**

L.N. Gumilyov Eurasian National University, Astana, Kazakhstan

E-mail: nugmanovagn@gmail.com

## Abstract.

In this paper we consider the coupled Kadomtsev-Petviashvili system. From compatibility conditions we obtain the form of matrix operators. After using a gauge transformation, obtained a new type of Lax representation for the hierarchy of Heisenberg ferromagnet equation, which is equivalent to the gauge coupled Kadomtsev-Petviashvili system.

## 1. Introduction

Korteweg-de Vries equation (KdV) is one of the most important equation in the theory of integrable systems, which have multi-soliton solution, an infinite number of conservation laws and many scientific applications [1].

In this paper we consider the expansion of the KdV equation - coupled Kadomtsev-Petviashvili equation (KP) with three potentials:

$$q_t = \frac{1}{4}(q_{xxx} - 6qq_x + 3 \int q_{yy} dx + 6(pr)_x), \quad (1)$$

$$p_t = \frac{1}{2}(-p_{xxx} - 6qp_x + 3qp_x + 3p \int q_y dx - 3p_{xy}), \quad (2)$$

$$r_t = \frac{1}{2}(-r_{xxx} + 3qr_x - 3r \int q_y dx + 3r_{xy}), \quad (3)$$

where indexes represent partial derivatives. This system is also integrable and can assume multi-soliton solutions [2].

By using certain transformations [3], the system (1)-(3) can be reduced to a coupled system of the KdV equation [4], and the standard KP equation [5].

The main goal of this paper is to construct the equivalent spin system to the coupled KP system through gauge transformation.

## 2. Searching unknown elements of matrix operators for the Lax representation

In [6] presented decomposed form of this system by the first two terms into (1+1) dimensional hierarchy of Ablowitz-Kaup-Newell-Sigur:

$$u_y = -u_{xx} + 2u^2v, \quad (4)$$



$$v_y = v_{xx} - 2uv^2, \tag{5}$$

$$u_t = u_{xxx} - 6uvu_x, \tag{6}$$

$$v_t = v_{xxx} - 6uvv_x \tag{7}$$

and offers the following assumption: if  $(u, v)$  is the solution of system (4)-(7), then the functions  $(p, q, r)$ , defined as  $q = 4uv, p = -2u^2, r = -2v^2$  is a solution of (1)-(3) [7].

The Lax representation of the system (4)-(7) is defined as

$$\Psi_x = U\Psi, \tag{8}$$

$$\Psi_y = V\Psi, \tag{9}$$

$$\Psi_t = W\Psi, \tag{10}$$

where  $U, V, W$  - matrix operators. Let  $U$  looks like:

$$U = -\frac{\lambda}{2}\sigma_3 + Q, \tag{11}$$

where  $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$  and  $Q = \begin{pmatrix} 0 & u \\ v & 0 \end{pmatrix}$ . Matrix operator  $V$  given in the form

$$V = \lambda^2 V_2 + \lambda V_1 + V_0, \tag{12}$$

where  $V_n = \begin{pmatrix} k_n & m_n \\ l_n & -k_n \end{pmatrix}$ ,  $n = 0, 1, 2$ . And operator  $W$  given by:

$$W = \lambda^3 W_3 + \lambda^2 W_2 + \lambda W_1 + W_0, \tag{13}$$

where  $W_m = \begin{pmatrix} a_m & b_m \\ c_m & -a_m \end{pmatrix}$ ,  $m = 0, 1, 2, 3$ . Let's find the unknown elements of given matrices  $V$  and  $W$ . For this purpose, we will use the compatibility conditions of the system (4)-(7) and after this we obtain that

$$U_y - V_x + [U, V] = 0, \tag{14}$$

$$U_t - W_x + [U, W] = 0, \tag{15}$$

$$V_t - W_y + [V, W] = 0. \tag{16}$$

From (14) after substitution matrix (11) and (12) we have

$$Q_y - (\lambda^2 V_2 + \lambda V_1 + V_0)_x - \frac{1}{2}[\sigma_3, V] + [Q, V] = 0, \tag{17}$$

from which we obtain next system of equations in powers of  $\lambda$ :

$$\lambda^3 : -\frac{1}{2}[\sigma_3, V] = 0, \tag{18}$$

$$\lambda^2 : -V_{2x} - \frac{1}{2}[\sigma_3, V_1] + [Q, V_2] = 0, \tag{19}$$

$$\lambda^1 : -V_{1x} - \frac{1}{2}[\sigma_3, V_0] + [Q, V_1] = 0, \tag{20}$$

$$\lambda^0 : Q_y - V_{0x} + [Q, V_0] = 0. \tag{21}$$

Consistently solving the equations (18) - (21) we determine the unknown elements and form of the matrix operator  $V$  as following

$$V = \begin{pmatrix} -\frac{\lambda^2}{2} + uv & \lambda u - u_x \\ \lambda v + v_x & \frac{\lambda^2}{2} - uv \end{pmatrix}. \quad (22)$$

From (15) in terms of matrices  $U, V, W$  we have

$$Q_t - (\lambda^3 W_3 + \lambda^2 W_2 + \lambda W_1 + W_0)_x - \frac{\lambda}{2} [\sigma_3, W] + [Q, W] = 0. \quad (23)$$

Expanding in powers of  $\lambda$ , we obtain the following equation:

$$\lambda^4 : -\frac{1}{2} [\sigma_3, W_3] = 0, \quad (24)$$

$$\lambda^3 : -W_{3x} - \frac{1}{2} [\sigma_3, W_2] + [Q, W_3] = 0, \quad (25)$$

$$\lambda^2 : -W_{2x} - \frac{1}{2} [\sigma_3, W_1] + [Q, W_2] = 0, \quad (26)$$

$$\lambda^1 : -W_{1x} - \frac{1}{2} [\sigma_3, W_0] + [Q, W_1] = 0, \quad (27)$$

$$\lambda^0 : Q_t - W_{0x} + [Q, W_0] = 0. \quad (28)$$

From the system of equations (24)-(28) we obtain the unknown elements and form of the matrix  $W$  as

$$W = \begin{pmatrix} -\frac{\lambda^3}{2} + uv\lambda - vu_x + uv_x & u\lambda^2 - u_x\lambda - 2u^2v + u_{xx} \\ v\lambda^2 + v_x\lambda - 2uv^2 + v_{xx} & \frac{\lambda^3}{2} - uv\lambda + vu_x - uv_x \end{pmatrix}. \quad (29)$$

Thus, we found all unknown elements of the matrix operators  $V, W$ .

### 3. The new Lax representation form and coupled KP equivalent spin system

Now we are ready to obtain the Lax representation of a desired spin system by using a gauge transformation in form

$$\Phi = g^{-1}\Psi. \quad (30)$$

By definition, gauge equivalence is  $g = \Psi|_{\lambda=0}$  and spin matrix is  $S = g^{-1}\sigma_3g$ .

After using a gauge transformation, we get a new Lax representation for the hierarchy of Heisenberg ferromagnet equation, which is the gauge equivalence of the coupled KP system (1)-(3).

New Lax representation looks like:

$$\Phi_x = -\frac{\lambda}{2} S\Phi, \quad (31)$$

$$\Phi_y = -\frac{\lambda^2}{2} S\Phi + \frac{\lambda}{2} SS_x\Phi, \quad (32)$$

$$\Phi_t = -\frac{\lambda^3}{2} S\Phi + \frac{\lambda^2}{2} SS_x\Phi - \frac{3\lambda}{8} tr(S_x^2)S\Phi - \frac{\lambda}{2} S_{xx}\Phi. \quad (33)$$

Using the conditions of compatibility of the Lax representation we obtain a new spin system. From first condition  $\Phi_{xy} = \Phi_{yx}$  after expanding by powers of  $\lambda$  we get the following equations:

$$S_x + \frac{1}{2} [SS_x, S] = 0, \quad (34)$$

$$S_y + \frac{1}{2} [S, S_{xx}] = 0. \quad (35)$$

From condition  $\Phi_{xt} - \Phi_{tx} = 0$ , expanding by powers of  $\lambda$  we have:

$$S_x + \frac{1}{2}[SS_x, S] = 0, \quad (36)$$

$$S_t - S_{xxx} - \frac{3}{4}tr(S_x^2)S_x - \frac{3}{4}[tr(S_x^2)]_x S = 0. \quad (37)$$

From the third conditions  $\Phi_{yt} - \Phi_{ty} = 0$ , expanding by powers of  $\lambda$  leads to the equations:

$$S_y + \frac{1}{2}[S, S_{xx}] = 0, \quad (38)$$

$$S_t + (SS_x)_y - \frac{3}{4}tr(S_x^2)S_x - \frac{1}{2}[S_{xx}, SS_x] = 0, \quad (39)$$

$$(SS_x)_t + S_{xxy} + \frac{3}{4}[tr(S_x^2)]_y S + \frac{3}{4}tr(S_x^2)S_y = 0. \quad (40)$$

Let us transform last two equations. After we consider (40)

$$S_t + (SS_x)_y - \frac{3}{4}tr(S_x^2)S_x - \frac{1}{2}[S_{xx}, SS_x] = 0. \quad (41)$$

In order to facilitate computations we divide this equation into the following two parts:

$$1) S_t - \frac{3}{4}tr(S_x^2)S_x = A, \quad (42)$$

$$2) (SS_x)_y - \frac{1}{2}[S_{xx}, SS_x] = B. \quad (43)$$

We consider the first term  $(SS_x)_y$ . Transform it considering the (35) and its derivative with respect to  $x$  ( $S_{xy} = S_{yx}$ ):

$$(SS_x)_y = S_y S_x + SS_{xy} = \frac{1}{2}[S_{xx}, SS_x] - \frac{1}{2}S_{xxx} + \frac{1}{2}SS_{xxx}S. \quad (44)$$

Substituting this in (43) we find that

$$-\frac{1}{2}S_{xxx} + \frac{1}{2}SS_{xxx}S = B. \quad (45)$$

The second term  $SS_{xxx}S$  we will express through the third derivative of the expression  $S \cdot S = I$ , multiplying it to  $S$ :

$$SS_{xxx}S = [S_{xx}S, S_x] - S_{xxx} - 2(S_x^2)_x S. \quad (46)$$

Substituting (46) into (45), we obtain

$$\frac{1}{2}[S_{xx}S, S_x] - S_{xxx} - (S_x^2)_x S = B. \quad (47)$$

Now we transform the first term of (47)  $\frac{1}{2}[S_{xx}S, S_x]$ :

$$\frac{1}{2}[S_{xx}S, S_x] = \frac{1}{2}(S_{xx}SS_x - S_xS_{xx}S) =$$

$$= \frac{1}{2}[(4uv g^{-1} \sigma_3 g + 2g^{-1} \begin{pmatrix} 0 & u_x \\ -v_x & 0 \end{pmatrix} g)g^{-1} \sigma_3 g \cdot 2g^{-1} \begin{pmatrix} 0 & u \\ -v & 0 \end{pmatrix} g - 2g^{-1} \begin{pmatrix} 0 & u \\ -v & 0 \end{pmatrix} g \cdot (4uv g^{-1} \sigma_3 g + 2g^{-1} \begin{pmatrix} 0 & u_x \\ -v_x & 0 \end{pmatrix} g)g^{-1} \sigma_3 g]. \quad (48)$$

As a result, we find that

$$\frac{1}{2}[S_{xx}S, S_x] = -\frac{1}{4}[tr(S_x^2)]_x S. \quad (49)$$

Substituting this expression in (47)

$$-S_{xxx} - \frac{1}{4}[tr(S_x^2)]_x S - (S_x^2)_x S = B. \quad (50)$$

Considering the third term as the  $(S_x^2)_x S = -(4uv)_x S = \frac{1}{2}[tr(S_x^2)]_x S$ , we get in result  $B$ :

$$-S_{xxx} - \frac{1}{4}[tr(S_x^2)]_x S - \frac{1}{2}[tr(S_x^2)]_x S = -S_{xxx} - \frac{3}{4}[tr(S_x^2)]_x S = B. \quad (51)$$

Add the  $A$  and  $B$ , according to (41) we obtain

$$S_t - S_{xxx} - \frac{3}{4}tr(S_x^2)S_x - \frac{3}{4}[tr(S_x^2)]_x S = 0, \quad (52)$$

which corresponds to the equation (37).

Now let's consider the equation (40)

$$(SS_x)_t + S_{xxy} + \frac{3}{4}[tr(S_x^2)]_y S + \frac{3}{4}tr(S_x^2)S_y = 0. \quad (53)$$

We will transform each term. Let's start with the first, taking into account the expressions for  $S_x$  and its derivative with respect to  $t$

$$(SS_x)_t = \frac{1}{2}S_t S_x + \frac{1}{2}S S_{xt} - \frac{1}{2}S_{xt} S - \frac{1}{2}S_x S_t, \quad (54)$$

$$\begin{aligned} \frac{1}{2}S_t S_x &= \frac{1}{2}S_{xxx} S_x + \frac{3}{8}[tr(S_x^2)]_x S S_x + \frac{3}{8}tr(S_x^2)S_x^2, \\ \frac{1}{2}S_x S_t &= \frac{1}{2}S_x S_{xxx} + \frac{3}{8}[tr(S_x^2)]_x S_x S + \frac{3}{8}tr(S_x^2)S_x^2. \end{aligned} \quad (55)$$

Due to the validity of the expression  $S_{xt} = S_{tx}$ :

$$\frac{1}{2}S S_{xt} = \frac{1}{2}S S_{xxx} + \frac{3}{4}[tr(S_x^2)]_x S S_x + \frac{3}{8}[tr(S_x^2)]_{xx} + \frac{3}{8}tr(S_x^2)S S_{xx}, \quad (56)$$

$$\frac{1}{2}S_{xt} S = \frac{1}{2}S_{xxx} S + \frac{3}{4}[tr(S_x^2)]_x S_x S + \frac{3}{8}[tr(S_x^2)]_{xx} + \frac{3}{8}tr(S_x^2)S_{xx} S. \quad (57)$$

Combining the above, we find that the first term  $(SS_x)_t$

$$(SS_x)_t = \frac{1}{2}[S_{xxx}, S_x] + \frac{1}{2}[S_x, S_{xxx}] \frac{9}{4}[tr(S_x^2)]_x S S_x + \frac{3}{8}tr(S_x^2)[S, S_{xxx}]. \quad (58)$$

Let's find the second  $S_{xxy} = S_{yxx}$ :

$$S_{yxx} = \frac{1}{2}[S_{xxxx}, S] + [S_{xxx}, S_x]. \quad (59)$$

By substituting the first two terms in the original equation (53), we obtain

$$\frac{3}{2}[S_{xxx}, S_x] + \frac{9}{4}[tr(S_x^2)]_x S S_x + \frac{3}{4}[tr(S_x^2)]_y S = 0. \quad (60)$$

We extend further transformation until we get in result the equation (37), or 0.

After the transformation of the first term, we have

$$\frac{3}{2}[S_{xxx}, S_x] = -\frac{9}{4}[tr(S_x^2)]_x S S_x + 6g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g. \quad (61)$$

Substituting the latest into (60) and obtain

$$\frac{3}{4}[tr(S_x^2)]_y S + 6g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g. \quad (62)$$

Transforming the first term, we find that

$$\frac{3}{4}[tr(S_x^2)]_y S = \frac{3}{2}(S_x S_x)_y S, \quad (63)$$

$$(S_x S_x)_y = S_{xy} S_x + S_x S_{xy} = -4g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g, \quad (64)$$

substituting the last expression into (63), and finally we find the following:

$$\frac{3}{4}[tr(S_x^2)]_y S = -\frac{3}{2}4g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g = -6g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g.$$

And finally substituting the last expression into (62), we obtain

$$-6g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g + 6g^{-1} \begin{pmatrix} -vu_{xx} + uv_{xx} & 0 \\ 0 & -v_{xx}u + vu_{xx} \end{pmatrix} g = 0. \quad (65)$$

Thus, in this paper was obtained integrable hierarchy of Heisenberg ferromagnet equation

$$S_t - S_{xxx} - \frac{3}{4}tr(S_x^2)S_x - \frac{3}{4}[tr(S_x^2)]_x S = 0, \quad (66)$$

which is the equivalent to a coupled KP system (1)-(3). Much more detailed study of the spin system (66) is the subject of our further research.

### Acknowledgments

We express gratitude to Professor R. Myrzakulov for useful discussions and advices. The work is performed under the financial support of the grant of MES RK GPh4-2016.

### 4. References

- [1] Wazwaz A 2011 *Pramana - journal of physics* **77** 233
- [2] Isojima S, Willox R and Satsuma J 2002 *Journal of Physics A: Mathematical and General* **35** 6893
- [3] Hirota R and Ohta Y 1991 *Journal of the Physical Society of Japan* **60** 798
- [4] David D, Levi D and Winternitz P 1987 *Studies in Applied Mathematics* **76** 133
- [5] Kakei S 2000 *Physics Letters A* **264** 449
- [6] Geng X G 2003 *Journal of Physics A: Mathematical and General* **36** 2289
- [7] Qi F-H, Tiana Bo, Liua W-J, Guoa R, Xua T and Zhanga H-Q 2011 *Verlag der Zeitschrift fur Naturforschung* Tubingen